







New micro size drive
of LS Industrial Systems

STARVERT iE5

Optimum solution for small size motor control

0.1~0.4kW 1Phase 200~230Volts
0.1~0.4kW 3Phase 200~230Volts

LS IS

Experience the power!



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Small but Powerful!

We have created the Micro class drive to provide
the optimal solution for small size motor controls.
You will be experiencing amazing power with this slim size.





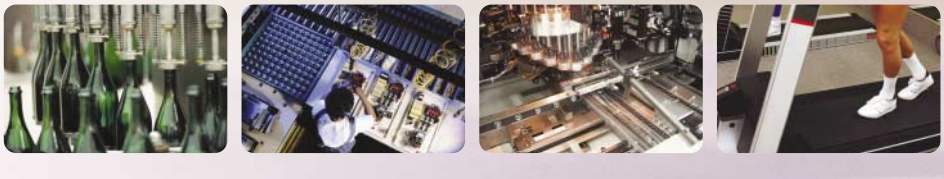
CE cULus ISO9001 ISO14000 STARVERT iE5

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Slim and variety!

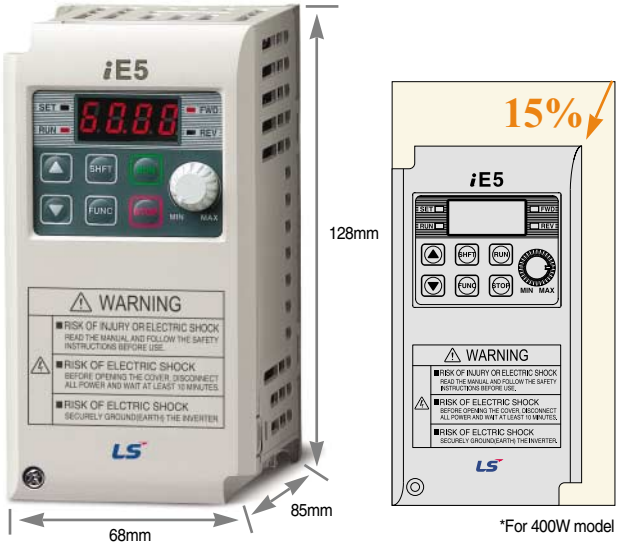
Our iE5 is best fit for small machineries

such as packing machines, small conveyers, treadmills and etc...



Smaller micro size

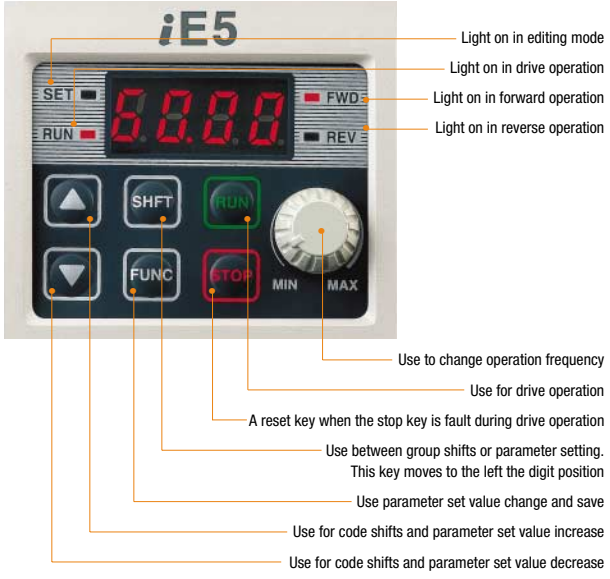
Our iE5 realizes 5% smaller micro size comparing to previous product.



SV002 iE5-1

Easy operation and control

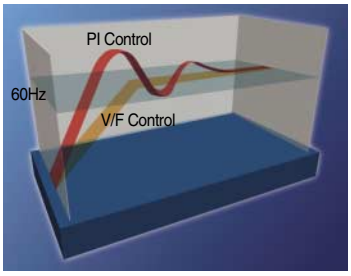
The operation became easy by adopting the 6 keys and volume resistor types on the loader. Besides, convenience is guaranteed by limiting the total number of parameters as 100 parameters.



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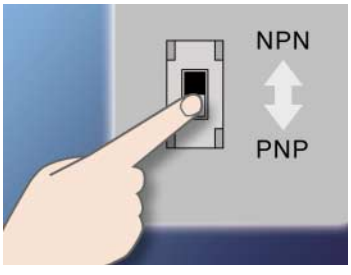


PI Control



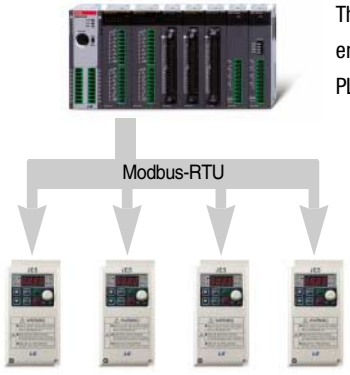
The PI Control is used to control the oil level, temperature and pressure of plant and process.This drive speed control function compares between drive setting value and signal values gauged from sensors and actual control is made through Proportion and Integral.

PNP, NPN dual control Signal



iE5 provides both PNP and NPN minor signal powers so that no matter what signal type the external controller adopts, +24V power can be applied.

Modbus communication interface (optional)



The optional modbus communication enables controlling drives through PLC and other controlling devices.

Parameter copy function (Under development)

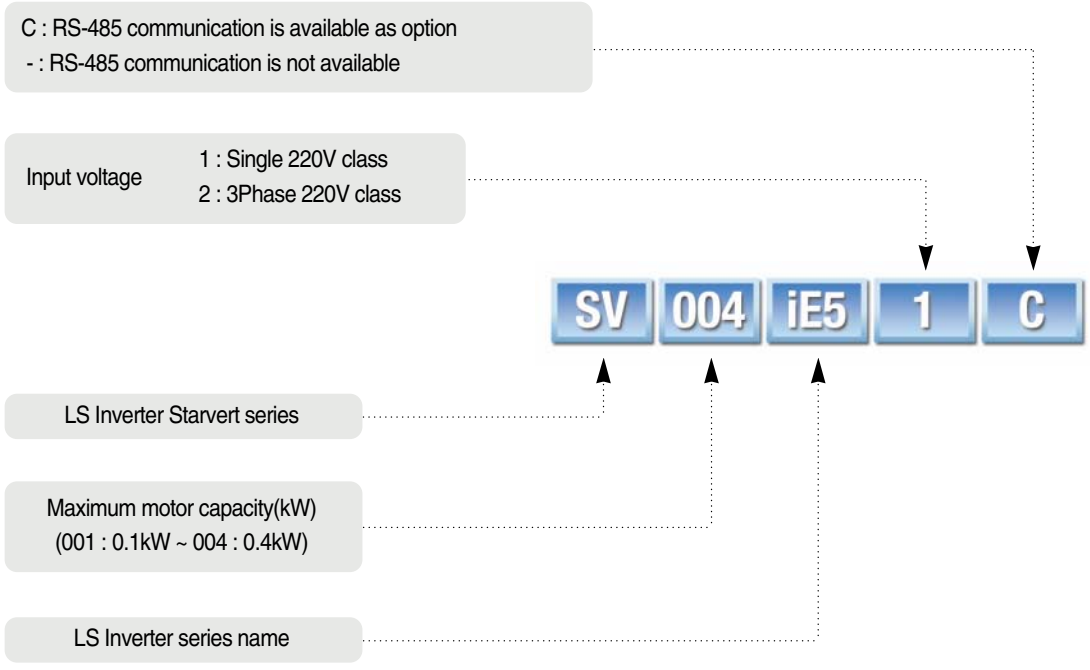


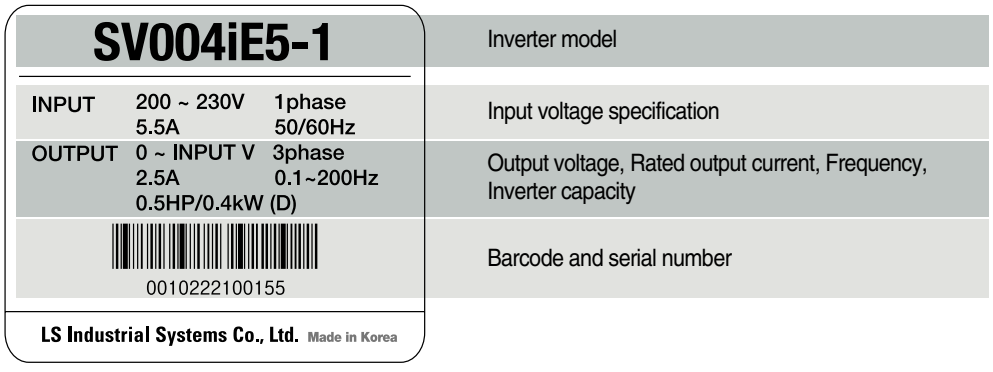
The parameters inputed to a drive can be duplicated and copied to other drives by this parameter copy unit.



Model and Specifications

Motor	220V(Single phase)	220V(3 phase)
0.1kW(1/8HP)	SV001 iE5-1	SV001 iE5-2
0.2kW(1/4HP)	SV002 iE5-1	SV002 iE5-2
0.4kW(0.5HP)	SV004 iE5-1	SV004 iE5-2





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Standard Specification

■ Basic specification

Model : SV□□□ iE5-□		001-1	002-1	004-1	001-2	002-2	004-2
Applicable motor	[HP]	1/8	1/4	1/2	1/8	1/4	1/2
	[kW]	0.1	0.2	0.4	0.1	0.2	0.4
Rated output	Rated capacity [kVA]	0.3	0.6	0.95	0.3	0.6	1.14
	Rated current [A]	0.8	1.4	2.5	0.8	1.6	3.0
	Output frequency [Hz]	0 ~ 200 [Hz]					
	Output voltage [V]	3 phase 200 ~ 230V					
Rated input	Applicable voltage [V]	1 phase 200 ~ 230 VAC (±10%)			3 phase 200 ~ 230 VAC (±10%)		
	Input frequency[Hz]	50 ~ 60 [Hz] (±5%)					
	Rated current [A]	2.0	3.5	5.5	1.2	2.0	3.5

■ Control

Control type	V/F Control
Frequency set resolution	Digital command : 0.01Hz Analog command : 0.06Hz (Max.frq : 60Hz)
Frequency accuracy	Digital command : 0.01% of Max. Output frequency Analog command : 0.1% of Max. Output frequency
V/F pattern	Linear, Squared, User V/F
Overload capacity	150% / 1Min
Torque boost	Manual / Auto torque boost

*Note1) The standard of rated capacity is 220V.
*Note2) The maximum output voltage does not increase over input voltage and the output voltage can be set below input voltage level.

■ Operation

Operation method		Operation method can be selected between loader, terminal and communication operation
Frequency set		Analog method : 0~10(V), 0~20(mA), Loader volume Digital method : Loader
Operation function		PI Control, Up-Down , 3-wire operation
Input	Multi-function terminal (5 points) P1,P2,P3, P4,P5	NPN / PNP Selectable
		FWD/REV operation, Fault reset, Jog operation, Multi-step frequency(up/down), DC braking in stop mode, Frequency increase, Frequency decrease, 3 wire-operation external trip A and B, Shift to general operation from PI operation. Analogue command frequency set, Up/down save frequency delete
	Multi-function relay terminal	Fault and drive operation condition output (N.). N.C) AC250V below 0.3A and below DC 30V 1A
	Analogue output	0~10Vdc(below 10mA) : can be selected among frequency, current, voltage, DC voltage

■ Protection

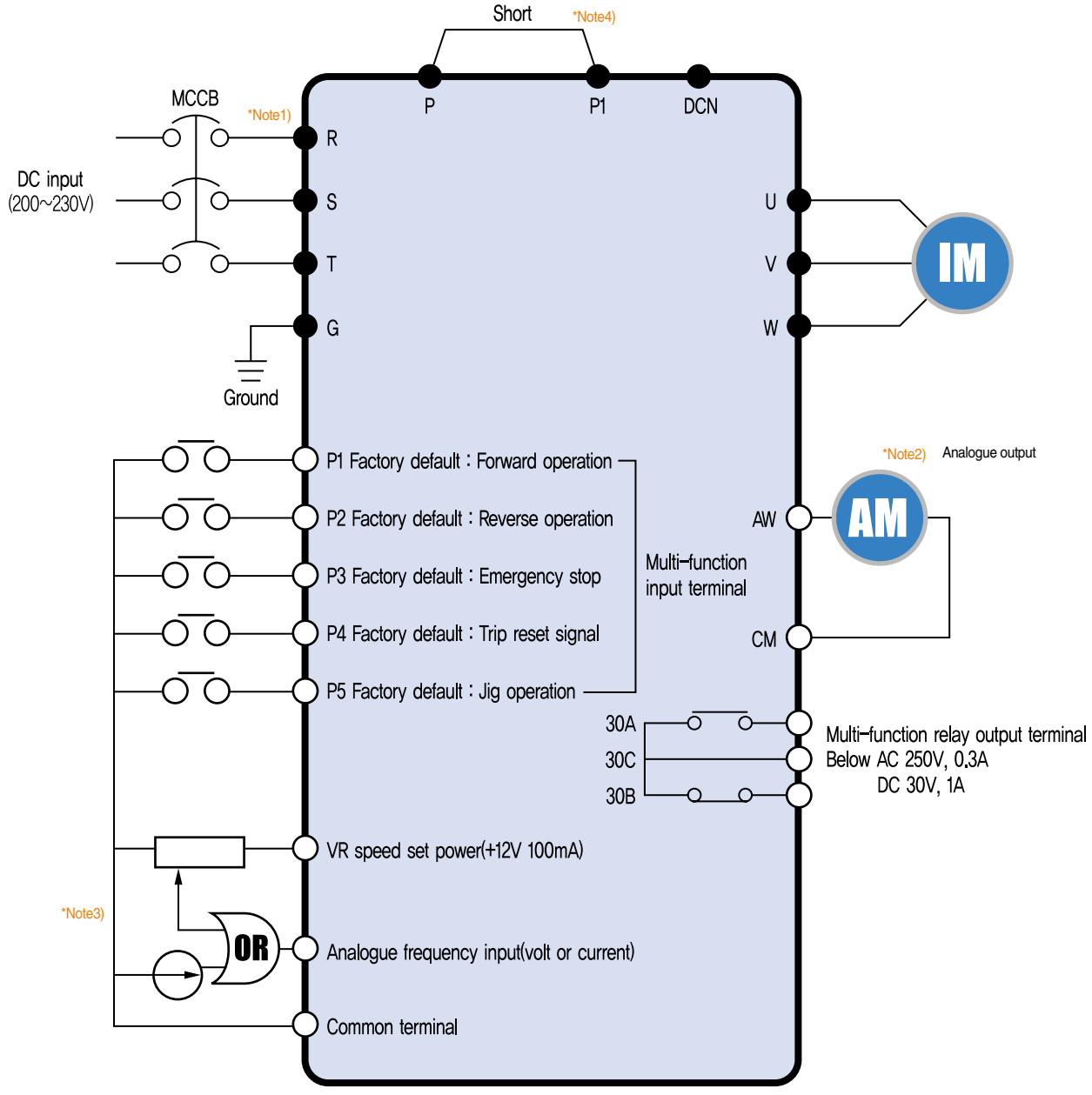
Trip	Over voltage, Under voltage, Over current, Ground fault, Drive overload, Overload trip, Overheat, Condensor overload, Phase loss overload protection, Frequency command loss, Hardware fault
Alarm	Stall prevention
Momentary power loss	Below 15msec : Operation continued (should be within rated input voltage and rated output) Over 15msec : Auto re-ignition operation.

■ Guaranteed operation condition

Cooling	Open cooling
Enclosure	IP20 (open type)
Ambient temperature	-10℃~65℃
Protection temperature	-20℃ ~ 65℃
Humidity	Below 90% RH (non-condensation)
Altitude/Vibration	Below 1000m, 5.9m/sec square (0.6G)
Installation condition	No corrosive gas, No flammable gas, No oil mist, No dust



Wiring



*Note1) "●" and "○" means the main circuit and the control circuit respectably.
Please connect to the R and S terminals in case of single phase use.
.*Note2) The analogue output is from zero to 10V.
*Note3) The voltage current and loader volume is possible for the external speed command.
*Note4) The P and PI terminals for DC reactor are connected as short circuit.

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Terminal Function

R S T P P1 DCN U V W

	Terminal signal	Terminal name	Description
Main circuit	R, S, T	DC input	Connect 3 phase AC power
	U, V, W	Inverter output	Connect 3 phase induced motor
	P, P1	DC reactor connection	Connect DC reactor.
	G	Ground	Ground connection terminal

*Note) Please connect to the R and S terminals for single phase drive.

P1 P2 P3 P4 P5 VR AI AM CM 30A 30B 30C

Classification	Terminal signal	Terminal name	Description
Input signal	P1, P2, P3, P4, P5	Multifunction input terminal	Factory default value P1 (FX : forward operation) P2 (RX : Reverse operation) P3 (EST : Emergency stop) P4 (RST : Trip clear signal) P5 (JOG : Jog frequency operation)
	VR	Frequency set power	Analog frequency set power. Max, output is +12V 100mA.
	AI	Frequency set(Volt/Current)	DC 0~10V and DC 4~20mA can be set as basic frequency.
	CM	Frequency set common terminal	Analog frequency set signal and AM common terminal.
Output signal	AM-CM	Display	Among output frequency, output current and output voltage, one item can be selected as output. Factory set is output frequency. Max output voltage is 0~10V. (Below 10mA)
	30A, 30C, 30B	Multifunctional relay	Inverter protection function is activated as blocking the output and releasing multifunction signal. AC 250V below 0.3A and below DC 30V 1A.

Loader Function



Classification	Display	Function	Function description
LED	FWD	Forward	Light is on with forward operation.
	REV	Reverse	Light is on with reverse operation.
	SET	On setting	Light is on when parameter is being set.
	RUN	On operation	Light is off when the inverter is on Acc/Dcc and on with normal speed operation.
KEY	▲	Up key	For code shift or increasing parameter set value.
	▼	Down key	For code shift or decreasing parameter set value.
	RUN	Operation key	For inverter operation
	STOP	Stop/Reset	Stop command key during operation and also used as fault clear key.
	FUNC	Function key	Used for changing parameter set value and saving its value
	SHFT	Shift key	Shift between groups and parameter setting or moving digit number to the left.
	Volume resistor		For changing operation frequency.
	NPN/PNP selection switch		Turning to either NPN or PNP mode.
	Current/Voltage selection switch		Switch for transforming the analog switch inputs into current or voltage.



Shifts between each code and group

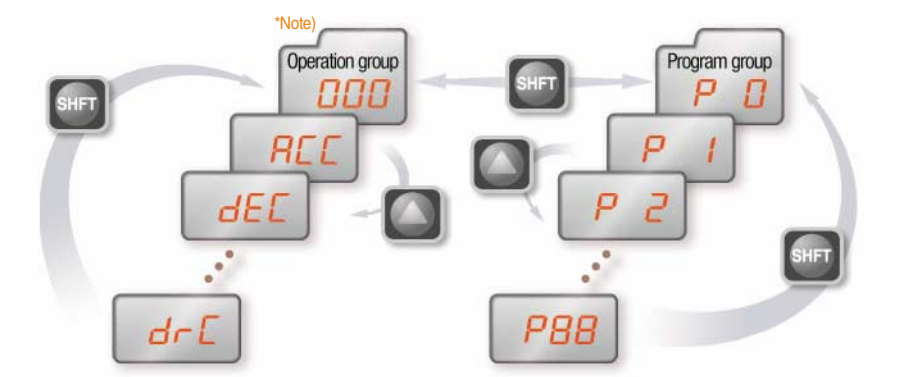
■ Diagram of function code shift method



The parameter group of iE5 consists of below two groups

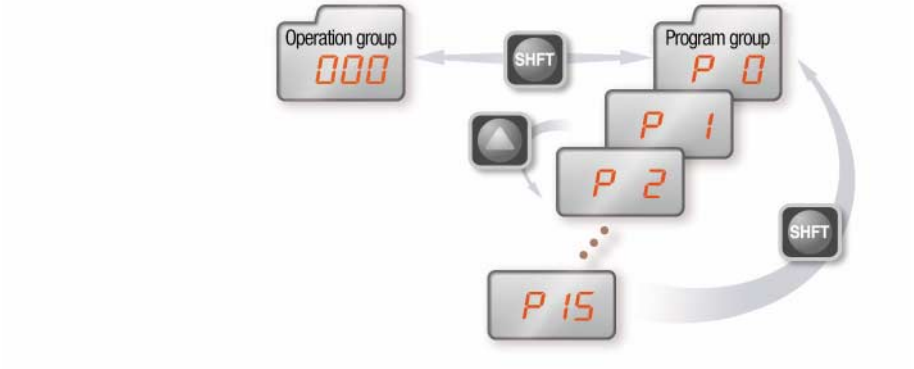
Group name	Content
Operation group	Basic parameters for operation such as the Target frequency, Acc/Dec time and etc.
Program group	Additional function set parameter

- **Shifts between groups can be enabled pressing the shift key at the zero code of the operation and program groups.**



*Note) The target frequency can be set at the first group of operation group so that the factory default value has been set as 0.0 yet in case of frequency change, the changed frequency is displayed.

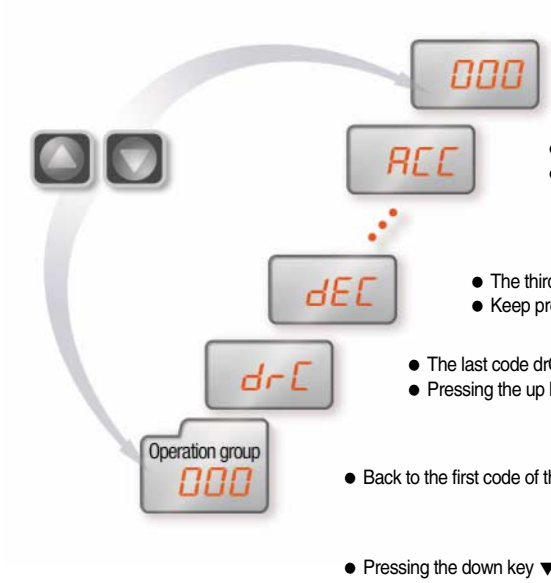
- **If a user presses the shift key out of number 0, the activating parameter shifts to 0 and if the user presses once more the shift key can be shifted between groups.**



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Shifts between each code and group

■ Operation group code shifts



- The first code 0.0 of operation group
- Press the up key ▲
- The second code ACC of operation group
- Press the up key ▲
- The third code dEC of operation group
- Keep pressing the up key ▲
- The last code drC of operation group
- Pressing the up key ▲ once again
- Back to the first code of the operation group
- Pressing the down key ▼ enables to shift reverse direction

■ Setting the operation group frequency to 30.05Hz (Keypad operation)



1 **0.00**
- Displays the first code information of the operation group
- Press the function key (FUNC)

2 **0.00**
- The setting light is off
- The second decimal point number can be changed
- Keep pressing the up key ▲ till the number reaches to 5

3 **0.05**
- Press the shift key
- The set number position shifts to left

3 **0.05**
- The set number position shifts to left
- Press twice the shift key

5 **00.05**
- The third last digit is changed as 0
- Set as 3 by pressing the up key ▲

6 **30.05**
- Press the function key (FUNC)

7 **30.05**
- Left displayed 30.05 blinks and asks if it has to be saved
- Press the function key (FUNC)

8 **30.05**
- The setting light (SET) is off
- Saved target frequency is displayed after stopping the light blink
- The saved data parameter is cancelled by pressing the Shift key (SHIFT), up key ▲ and then the down key ▼

*Note) The saved parameter can be cancelled by pressing all keys except the function key (FUNC).



Parameter Descriptions

■ Operation group

Display	Function	Setting range	Description	Factory default	Mode change during run
0.0	Command frequency	0 ~ 200 [Hz]	Operation frequency set. Displays the command frequency during stop mode and displays the output frequency during run In case of multi-speed operation, the frequency will be zero speed. The frequency setting can not be set over the maximum frequency(P16).	0.0	○
ACC	Acceleration time	0 ~ 6000 [sec]	Zero times acc/dec time in case of multi-step speed acc/dec.	5.0	○
dEC	Acceleration time			10.0	○
drv	Operation command method	0 ~ 3	0 : Operation using the RUN key and the STOP key of loader 1 : Terminal operation : FX : Forward operation command, RX : Reverse operation command 2 : Terminal operation : FX : Operation and Stop command, RX : Selecting reverse 3 : Communication operation: Operation by communication	1	×
Frq	Frequency setting method	0 ~ 4	0 : Digital : Loader digital frequency setting 1 1 : Digital : Loader digital frequency setting 2 2 : Analog : Terminal AI input 3 : Analog : Loader volume resistor 4 : Analog : Communication option	0	×
St1	Multi step frequency 1	0 ~ 200 [Hz]	Speed 1 frequency set in case of multi step operation	10.0	○
St2	Multi step frequency 2		Speed 2 frequency set in case of multi step operation	20.0	○
St3	Multi step frequency 3		Speed 3 frequency set in case of multi step operation	30.0	○
CUr	Output current	-	Output current display	-	-
rPM	No of times of motor spin	-	Displaying no of time of motor spin(RPM)	-	-
dCL	Inverter DC voltage	-	Displaying the DC link voltage of inverter inside	-	-
vOL	Output voltage	-	Displaying output voltage	vOL	-
nOn	Fault status	-	Displaying the trip type, frequency, current and operation condition of trip	-	-
drC	Spin direction selection	F, r	Setting the operation command method as 0 F : Forward operation r : Reverse operation	P	○

■ Program group

Display	Function	Setting range	Description	Factory default	Mode change during run
P0	Jump code	0 ~ 88	Shifting code number set	1	○
P1	Fault history 1	-	Fault type and frequency, current, acc/dec and stop condition of fault. The latest fault is saved as fault history no 1.	nOn	-
P2	Fault history 2	-		nOn	-
P3	Fault history 3	-		nOn	-
P4	Fault history delete	0 ~ 1	Deleting the fault history P1~P3	0	○
P5	Forward/Reverse not allowed	0 ~ 2	0 : Forward/Reverse spining is possible 1 : Forward spinning not allowed 2 : Reverse spinning not allowed	0	×
P6	Acceleration pattern	0 ~ 1	0 : Liner pattern operation 1 : S shape pattern operation	0	×
P7	Deceleration pattern				
P8	Stop mode selection	0 ~ 2	0 : Deceleration stop 1 : DC braking stop 2 : Free run stop	0	×
P9	DC braking frequency	0.1 ~ 60 [Hz]	DC braking start frequency. DC braking frequency can not be set below the starting frequency P18.	5.0	×

*Note1)

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Parameter Descriptions

■ Program group

*Note1)

Display	Function	Setting range	Description	Factory default	Mode change during run
P10	Output block time before DC braking	0 ~ 60 [sec]	Output is blocked for set up time and starts DC braking.	0.1	×
P11	DC braking volume	0 ~ 200 [%]	DC current size that flows to motor. The standard is motor rated current (P43).	50	×
P12	DC braking time	0 ~ 60 [sec]	DC time that flows to motor.	1.0	×
P13	DC braking volume at ignition	0 ~ 200 [%]	DC current volume that flows to motor before it spins. Motor rated current (P43).	50	×
P14	DC braking time of ignition	0 ~ 60 [sec]	DC current flows to motor for scheduled time at ignition.	0	×
P15	Jog frequency	0 ~ 200 [Hz]	Jog operation frequency can be set. The frequency can not be set over maximum frequency(P16).	10.0	○
P16	Maximum frequency	40 ~ 200 [Hz]	Frequency setting related maximum value of parameters. The standard frequency of Acc/Dec lean. ☞ Note : Once the maximum frequency value is changed, all parameter values other than P17(standard frequency) are changed as the maximum frequencies that are all over the maximum frequencies.	60.0	×
P17	Standard frequency	30 ~ 200 [Hz]	The output frequency within which the inverter output equals to the rated voltage of motor.	60.0	×
P18	Starting frequency	0.1 ~ 10 [Hz]	The minimum parameter value of frequency level.	0.5	×
P19	Torque boost selection	0 ~ 1	0 Manual torque boost 1 Automatic torque boost	0	×
P20	Forward operation torque boost	0 ~ 15 [%]	The boost volume, in case of forward operation, that flows to motor. In case of maximum output voltage.	5	×
P21	Reverse operation torque boost	0 ~ 15 [%]	The boost volume, in case of reverse operation, that flows to motor. The maximum output voltage is standard.	5	×
P22	V/F pattern	0 ~ 1	0 Liner 1 Square	0	×
P23	Output voltage control	40 ~ 110 [%]	Output voltage size control. The input voltage is standard.	100	×
P24	Overload trip selection	0 ~ 1	Blocking the inverter output in case of overload. The overload protection function is activated if user sets as umber 1.	1	○
P25	Overload trip level	50 ~ 200 [%]	Overload current size setting. Motor rated current (P43) is standard.	180	○
P26	Overload trip time	0 ~ 60 [sec]	Inverter blocks output if the overload trip level(P25) current flows for the overload trip time.	60	○
P27	Stall prevention selection	0 ~ 7	Decelerating in acceleration or normal operation. Deceleration is stopped during deceleration operation. 0: - - - 1: - - v 2: - v - 3: - v v 4: v - - 5: v - v 6: v v - 7: v v v (Stall prevention during deceleration / Stall prevention during normal deceleration / Stall prevention during acceleration deceleration; bit 2 / bit 1 / bit 0)	0	×
P28	Stall prevention level	30 ~ 150 [%]	Displaying the stall prevention current size during acceleration or normal operation in terms of percent(%). The motor rated current(P43) is standard.	150	×
P29	Up/Down frequency save selection	0 ~ 1	Selecting the set frequency for up/down operation. If user chooses number 1, it is saved onto up/down frequency(P30).	0	×
P30	Up/Down frequency save	-	Displaying up/down operation stop or before acceleration frequency.	0.00	-
P31	Dwell frequency	0.1 ~ 200 [Hz]	Once operation command is inputted, first outputs the dwell frequency during dwell time(P32) and then starts acceleration. Dwell value can be set between the maximum frequency P16 and starting frequency P18.	5.0	×
P32	Dwell time	0~10 [sec]	Dwell operation time setting	0.0	×

*Note1) The P8 has to be set as 1 (DC braking stop)



Parameter Descriptions

■ Program group

<table>
<tr><th>Display</th><th>Function</th><th>Setting range</th><th>Description</th><th>Factory default</th><th>Mode change during run</th></tr>
<tr><td>P33</td><td>User selection fault detect</td><td>0 ~ 7 [bit]</td><td>Setting the fault detect item as per user selection.
The input/output phase loss, ground detect during run can be selected.
<table><tr><th>User selection fault detect [Trip]</th><th>Ground detect during run GCt</th><th>Input phase loss detect CoL</th><th>Output phase loss detect(Pot)</th></tr><tr><td></td><td>bit 2</td><td>bit 1</td><td>bit 0</td></tr><tr><td>0</td><td>-</td><td>-</td><td>-</td></tr><tr><td>1</td><td></td><td></td><td>v</td></tr><tr><td>2</td><td></td><td>v</td><td></td></tr><tr><td>3</td><td></td><td>v</td><td>v</td></tr><tr><td>4</td><td>v</td><td></td><td></td></tr><tr><td>5</td><td>v</td><td></td><td>v</td></tr><tr><td>6</td><td>v</td><td>v</td><td></td></tr><tr><td>7</td><td>v</td><td>v</td><td>v</td></tr></table></td><td>0</td><td>○</td></tr>
<tr><td>P34</td><td>Selecting start with power input</td><td>0 ~ 1</td><td>P34 is only used in case the operation command method is selected.
Either terminal number 1 or 2. Acceleration is getting started when the FX or RX terminal is on with power input.</td><td>0</td><td>×</td></tr>
<tr><td>P35</td><td>Selecting start after trip</td><td>0 ~ 1</td><td>P34 is only used in case the operation command method is selected either terminal number 1 or 2.
In the condition that the FX and RX terminals are on, after trip, resetting starts acceleration.</td><td>0</td><td>○</td></tr>
<tr><td>P36</td><td>Speed search selection</td><td>0 ~ 15 [bit]</td><td>While motor is on spining, this function prevents the probable faults.
<table><tr><th></th><th>Starting with power input(P34)</th><th>Restart after instant power failure</th><th>Operation after trip (P35)</th><th>General Acceleration</th></tr><tr><td></td><td>bit 3</td><td>bit 2</td><td>bit 1</td><td>bit 0</td></tr><tr><td>0</td><td>-</td><td>-</td><td>-</td><td>-</td></tr><tr><td>1</td><td>-</td><td>-</td><td>-</td><td>v</td></tr><tr><td>2</td><td>-</td><td>-</td><td>v</td><td>-</td></tr><tr><td>3</td><td>-</td><td>-</td><td>v</td><td>v</td></tr><tr><td>4</td><td>-</td><td>v</td><td>-</td><td>-</td></tr><tr><td>5</td><td>-</td><td>v</td><td>-</td><td>v</td></tr><tr><td>6</td><td>-</td><td>v</td><td>v</td><td>-</td></tr><tr><td>7</td><td>-</td><td>v</td><td>v</td><td>v</td></tr><tr><td>8</td><td>v</td><td>-</td><td>-</td><td>-</td></tr><tr><td>9</td><td>v</td><td>-</td><td>-</td><td>v</td></tr><tr><td>10</td><td>v</td><td>-</td><td>v</td><td>-</td></tr><tr><td>11</td><td>v</td><td>-</td><td>v</td><td>v</td></tr><tr><td>12</td><td>v</td><td>v</td><td>-</td><td>-</td></tr><tr><td>13</td><td>v</td><td>v</td><td>-</td><td>v</td></tr><tr><td>14</td><td>v</td><td>v</td><td>v</td><td>-</td></tr><tr><td>15</td><td>v</td><td>v</td><td>v</td><td>v</td></tr></table></td><td>0</td><td>○</td></tr>
<tr><td>P37</td><td>Speed search current level</td><td>80 ~ 200 [%]</td><td>The current size during speed search operation is limited.
Motor rated current(P43) is standard.</td><td>100</td><td>○</td></tr>
<tr><td>P38</td><td>Number of times of Auto-restart</td><td>0 ~ 10</td><td>Setting number of times that drive can operate automatically after trip.
If trips exceed the set times, drive does not restart automatically. Only use when the operation command method(drv) of operation group is selected either terminal umber 1 or 2 and the operation command is inputted.
However, the Auto-restart does not work in case the protective functions such as OHT, LVT, EST and HWT are in active.</td><td>0</td><td>○</td></tr>
<tr><td>P39</td><td>Auto re-start stand by time after trip</td><td>0 ~ 60 [sec]</td><td>Re-start is operated after the auto re-start stand-by time of trip.</td><td>1.0</td><td>○</td></tr>
<tr><td>P40</td><td>Motor capacity selection</td><td>0.1 ~ 0.4</td><td></td><td>- *Note2)</td><td>×</td></tr>
<tr><td>P41</td><td>Number of poles of motor</td><td>2 ~ 12</td><td>Used for number of spining times of motor of the operation group.</td><td>4</td><td>×</td></tr>
</table>

*Note2) The initial value of P40 is set for the drive capacity.

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Parameter Descriptions

■ Program group

Display	Function	Setting range	Description	Factory default	Mode change during run
P42	Motor rating Slip frequency	0 ~ 10 [Hz]	The difference value between input power frequency and motor name plate displayed rated spin times(rpm) is inputted.	- *Note3)	×
P43	Motor rated current	0.0 ~ 25.5 [A]	The printed rated current value of name plate is inputted.	-	×
P44	Non-load current of motor	0.0 ~ 25.5 [A]	After taking out load from motor, the current value which was measured in operation condition of rated spin times is inputted.	-	×
P45	Carrier frequency selection	1 ~ 10 [kHz]	As the set carrier value is larger the noise is smaller but the leaking current is bigger.	3	○
P46	Control type selection	0 ~ 2	0 V/F control 1 Slip compensation control 2 PI control	0	×
P47	PI control P gain	0 ~ 999.9 [%]	Gain setting for PI control response.	300.0	○
P48	PI control I time	0.1~32.0 [sec]		1.0	○
P50	PI control F gain	0 ~ 99.99 [%]	Feed forward of PI control	0.0	○
P51	PI frequency highest limit	0.1 ~ 200 [Hz]	Limits the frequency size that comes from PI calculation. The setting value can be between the maximum frequency(P16) and starting frequency(18).	60.0	○
P52	PI frequency lowest limit	0.1 ~ 200 [Hz]		5.0	○
P53	Power input display selection	0 ~ 15	First displayed items on the loader with power input. 0 Operation frequency 1 Acceleration time 2 Deceleration time 3 Operation command method 4 Frequency command method 5 Multi-step frequency 1 6 Multi-step frequency 2 7 Multi-step frequency 3 8 Output current (Cur) 9 Number of times of motor spin(rpm) 10 Drive DC voltage (DCL) 11 User selection (vOL) 12 Fault status 1 13 Operation direction selection 14 Output current display 15 Displaying number of times of motor spin	0	○
P54	Gain of number of times of motor	1 ~ 1000 [%]	By calculating the gear rate of load system, displays the number of times of motor. Monitoring is possible at the (rPM) code.	100	○
P55	Constant number of AI filter input	0 ~ 9999	Controlling the analog input response.	10	○
P56	Minimum input of AI	0 ~ 100 [%]	Minimum analog input value can be set as % of total input.	0	○
P57	AI input maximum voltage matching	0 ~ 200	Analog input minimum case frequency.	0.0	○
P58	AI maximum input	0 ~ 100 [%]	The maximum analog input value can be set as all input percent(%).	100	○
P59	AI input maximum voltage matching frequency	0 ~ 200 [Hz]	The maximum frequency value of analog input.	60.0	○
P60	Volume input filter constant	0 ~ 9999	Response speed control of volume input operation.	10	○
P61	Volume input minimum value	0 ~ 100 [%]	The volume input minimum spin value can be set as all input percent(%).	0	○
P62	Volume input maximum voltage matching frequency	0 ~ 200 [Hz]	Volume input minimum value frequency.	0.0	○
P63	Volume input maximum value	0 ~ 100 [%]	The volume input maximum value can be set as all input percent(%).	100	○
P64	Volume input maximum voltage machine frequency	0 ~ 200 [Hz]	The volume input maximum value frequency.	60.0	○
P65	Phase loss standard selection of analog speed command	0 ~ 2	0 No operation 1 Operation below half value of set 2 Operation below set value	0	○

*Note3) All the values from P42 and P44 are modified to adopt the motor capacity P40.



Parameter Descriptions

■ Program group

Display	Function	Setting range	Description	Factory default	Mode change during run
P66	Multi-function input terminal P1 function	0 ~ 24	0 Forward operation command(FX) 1 Reverse operation command(RX)	0	○
P67	Multi-function input terminal P2 function		2 Emergency stop(EST-Emergency stop trip) : Temporal output block.	1	○
P68	Multi-function input terminal P3 function		3 Fault reset (RST) 4 Jog operation command (JOG)	2	○
P69	Multi-function input terminal P4 function		5 Multi-step frequency-up 6 Multi-step frequency-down	3	○
P70	Multi-function input terminal P5 functions		7 - 8 - 9 - 10 - 11 DC braking command 12 - 13 - 14 - 15 Up-down operation function: Frequency up 16 Up-down operation function: Frequency down 17 3-wire operation. 18 External trip signal input : A contact (EtA) 19 External signal input : B contact (EtB) 20 Changing operation mode from PI to normal operation. 21 Changing operation mode from option operation to master operation. 22 Analog command frequency fix 23 Acc/Dec stop command 24 Up/Down frequency delete	4	○
P71	Input terminal status display		BIT4 BIT3 BIT2 BIT1 BIT0 P5 P4 P3 P2 P1	-	-
P72	Multi-function input filter constant	1 ~ 20	Bigger setting value resets in slower response speed.	15	○
P73	Analog output item selection	0 ~ 3	Output item / Matching output 10[V] 0 Output frequency / Maximum frequency 1 Output current / 150% 2 Output voltage / 282V 3 Drive DC voltage / DC 400V	0	○
P74	Analog output level control	10 ~ 200 [%]	10V is standard	100	○
P75	Detected frequency	0 ~ 200 [Hz]	Please use when the output terminal function of relay output(P77) is chosen from 0~4.	30.0	○
P76	Detectable frequency range		No more than the maximum frequency(P16) can be set.	10.0	○
P77	Multifunctional relay terminal function selection	0 ~ 17	0 FDT-1 1 FDT-2 2 FDT-3 3 FDT-4 4 FDT-5 5 Overload (OL) 6 Drive overload (IOLt) 7 Motor stall (STALL) 8 Overvoltage fault (OVt) 9 Low voltage fault (LVt) 10 Cooling pin overheat (OHt) 11 Command loss 12 On operation 13 On stop 14 On normal operation 15 Speed search function is on 16 Operation command is ready 17 Fault output selection	17	○

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Parameter Descriptions

■ Program group

Display	Function	Setting range	Description	Factory default	Mode change during run
P78	Fault output selection	0 ~ 7 [bit]	After trip, when the number of Auto restart is set, P38 is activated (bit 2); Except low voltage trip, in all other cases this function is activated (bit 1); This function is activated with low voltage trip (bit 0) 0: - - - 1: - - v 2: - v - 3: - v v 4: v - - 5: v - v 6: v v - 7: v v v	2	○
P79	Drive channel	1 ~ 250	Use with communication option	1	○
P80	Communication speed	0 ~ 2	Communication speed set 0: 2400 [bps] 1: 4800 [bps] 2: 9600 [bps]	2	○
P81	Operation type selection when the speed command is lost	0 ~ 2	This function is used when the analog signal of terminal (Volume or AI) or communication are operated by frequency command. 0: Operating before command loss frequency 1: Free run stop (Blocking output) 2: Deceleration stop	0	○
P82	Speed command loss determination time	0.1 ~ 120 [sec]	If the frequency command is not inputted during speed command loss determination time the drive is operated by P81 selected operation way.	1.0	-
P83	Communication stand-by time	2 ~ 100 [ms]	In case of RS 485 communication, setting the stand-by time to the next TX output after TX signal.	5	
P84	Parity/STOP setting	0 ~ 3	Communication parity and STOP bit are set like following. 0: - 1 Stop bit 1: - 2 Stop bit 2: Odd Parity 1 Stop bit 3: Even Parity 1 Stop bit	0	
P85	Parameter Initializing	0 ~ 3	User modified parameters can be initialized as factory default values. 0: - 1: 2 Groups' parameters initialization 2: Operation groups' parameters initialization 3: Program group parameters initialization	0	×
P86	Password registration	0 ~ FFFF	Password inputted to prohibit the parameter change and values are set as HEXA.	0	○
P87	Parameter change prohibition	0 ~ FFFF	The parameter change prohibition can be executed or cleared by the password. UL(Unlock): Parameter change is allowed L(Lock): Parameter change is prohibited	0	○
P88	Version of Software	-	Displays the SW version of drive. Please refer to the manual version.	-	×



Protections

Display	Protections	Descriptions
OCt	Over current	Drive output is blocked in case the output current is over 200% of rated current.
GFt	Ground current	In case the ground protection of starting point is used, the drive output is blocked if ground current flows that is generated from the drive output side.
GCt	Ground current	Drive blocks its output if the over current is flowed to any phase of between U.V.W phase. In this case the over current is generally generated by unbalancing from ground fault.
I OL	Overload	If the output current of drive is over 150% of rated current for more than one minute, the output is blocked. The protection time is shortened as output current is increased
OLt	Overload trip	If output current is bigger than motor rated current(P25) the output is blocked
OHt	Cooling fan overheat	If the drive cooling fan is overheated, and if the ambient temperature of drive reaches to over recommended degree, the output of drive is blocked.
COL	Condenser overload	This fault is generated in case of single phase loss of three phase product or if DC voltage fluctuation level becomes big as the main condenser is aged. Yet the condenser overload detection time can be varied depend on the output current size.
POt	Output loss	More than one phase becomes loss among U.V.W, the drive output is blocked.
Out	Over voltage	If the main circuit DC voltage of drive inside goes over 400V, the output is blocked. This over voltage is generated if the deceleration time is too short or the input voltage goes over recommended level.
Lut	Low voltage	If drive inside main circuit voltage goes below 180V, drive blocks its output.
EEP	Parameter save fault	When the changed parameter is inputted to drive, if some faults are generated, this fault is displayed. This is displayed with power input.
HWt	Hardware fault	This is displayed with CPU or OS fault. This is not cleared by the STOP/RST key of loader or by the reset terminal. Fault is not cleared by STOP/RST keys of the keypad or reset terminal. Please re-input power after off the drive power and the keypad display power is completely off.
ESt	Output instant blocking	Drive output is blocked when the EST terminal is on. ⚠ Caution : with the "ON" of terminal operation command signal FX or RX, if the EST terminal is off drive restart its operation.
EtA	A Contact fault signal input	Once the multi-function input terminal selection(P66~P70) is selected as number 18 (External trip signal input : A contact) and if this selected becomes "OFF" the drive blocks output.
Etb	A Contact fault signal input	Once the multi-function input terminal selection(P66~P70) is selected as number 19 (External trip signal input : B contact) and if this selected becomes "OFF" the drive blocks output.
_ _ _L	Frequency phase loss	Displays fault status of frequency command. In case the analog input(0~10V), 0~20mA and option(RS485)operation, if the operational signal is not inputted, the operation is carried out by P81 that is selected from the speed command phase loss operation.

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Check and Remedy

Protections	Fault reason	Remedy
Caution	The fault caused by over current may damage drive inside power semiconductor parts so that the reason of over current has to be cleared first and then start operation.	
OCt Over current	• Acc/Dec time is too fast comparing to the load inertia(GD2) • Load is bigger than rated value. • Drive output is released during free run of motor. • Output terminal and ground fault. • Motor breaking is too speedy.	▸ Please set the Acc/Dec time with higher margin. ▸ Please replace bigger capacity drive. ▸ Try to operate after stopping motor or please use the speed search function(H22) of function group 2. ▸ Please check the output wiring. ▸ Please check the mechanical break.
GFt GCt Ground current	• Drive outputcable is on ground fault. • Motor insulation is heated.	▸ Please check the output terminal wiring. ▸ Please replace the motor.
IOL OLt Drive overload Overload trip	• Load is bigger than rated value. • Torque boost volume is too big.	▸ Please use higher capacity motor and drive. ▸ Please reduce the torque boost volume.
OHt Cooling fan overheat	• Cooling system fault. • Cooling fan lifetime is over. • High ambient temperature.	▸ Please check the vents. ▸ Please replace cooling fan. ▸ Please keep the ambient temperature to 40℃.
COL Condenser overload	• 1 phase is loss of three phase product. • Internal condenser life is over.	▸ Please check input power wiring. ▸ Please check the input power. ▸ Replacement may need please ask after sales service.
POt Output phase loss	• Electronic contactor fault of output part. • Output wiring fault.	▸ Please check the electronic contactor of output part. ▸ Please check the output part wiring.
Out Over voltage	• Dec time is too short comparing to the load inertia(GD2). • Regenerative load is located at the output part. • Main power is to high.	▸ Please set the deceleration time with higher margin. ▸ Please down the main power below rated value.
Lut Low voltage	• Main power is too low. • Bigger than power capacity load is contacted to the main power part. • Electronic contactor fault of power part.	▸ Please use over rated value power. ▸ Please use higher power. ▸ Please replace the electronic contactor.
EtA A contact fault signal input Etb B contact fault signal input	• When the multi-function input terminal selection of the program group(P66~P70) is set as number 18 or 19 if these terminals are "ON" these fault messages are displayed.	▸ Circuit fault and external faults.
_ _ _ L Frequency command loss	• No command at the V1 and I terminals. • No signal input of communication option.	▸ Please check the wiring and command level of V1 and I terminals. ▸ Please check the communication cable of the master device.
EEP Parameter save fault HW Hardware fault		▸ After software upgrade when the power is inputted as first time, these messages are displayed. In this case, please "OFF" the power first and then re-input the power. This is normal operation after software upgrade.



Peripheral device specifications

■ MCCB and MC standards

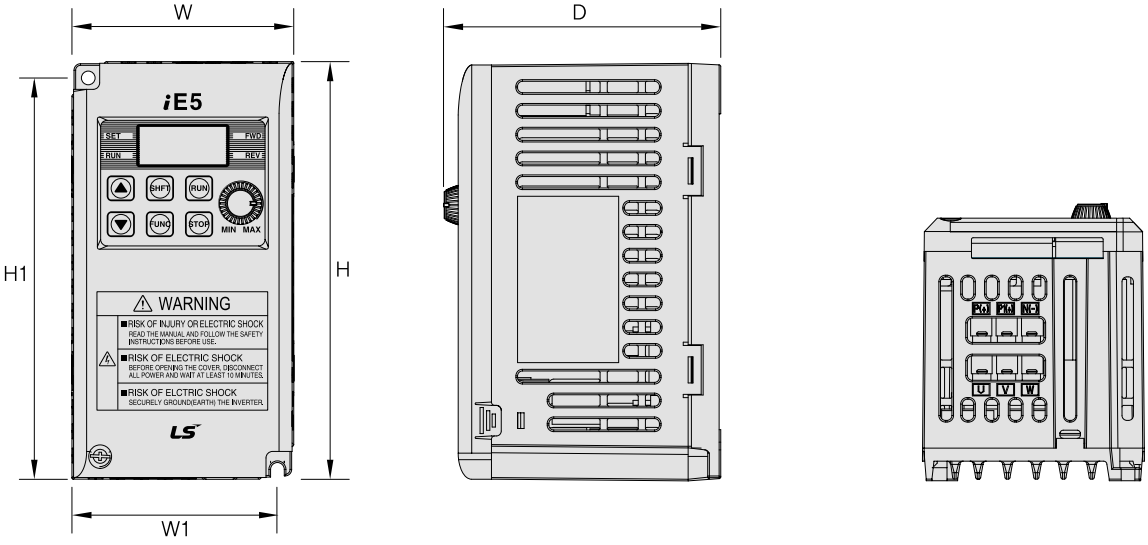
Drive capacity	MCCB(LSIS)		ELCB(LSIS)		MC(LSIS)	
001 iE5-1	ABS33b	5A	EBS33b	5A	GMC-9	7A
002 iE5-1		10A		10A	GMC-12	9A
004 iE5-1		15A		15A	GMC-18	13A
001 iE5-2		3A		3A	GMC-9	7A
002 iE5-2		5A		5A	GMC-9	7A
004 iE5-2		10A		10A	GMC-12	9A

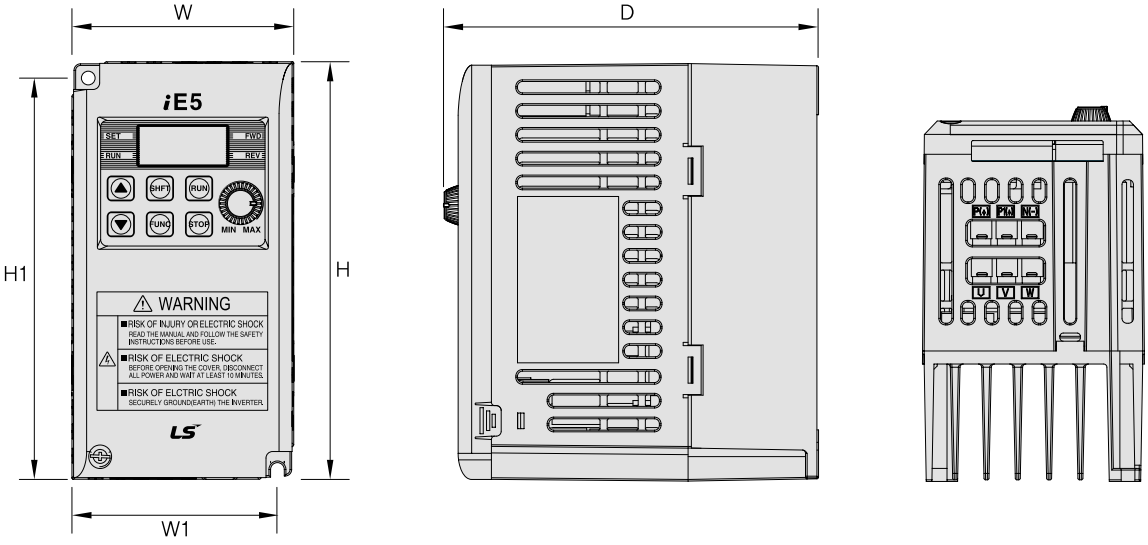
■ Reactor specification

Drive capacity	AC input fuse	AC reactor	DC reactor
001 iE5-1	5A	4.2mH, 3.5A	10mH, 3A
002 iE5-1	5A	4.2mH, 3.5A	10mH, 3A
004 iE5-1	10A	5.1mH, 5.4A	7mH, 5A
001 iE5-2	5A	4.2mH, 3.5A	10mH, 3A
002 iE5-2	5A	4.2mH, 3.5A	10mH, 3A
004 iE5-2	5A	4.2mH, 3.5A	7mH, 5A

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Dimension





Measure	001 iE5-1	002 iE5-1	004 iE5-1	001 iE5-2	002 iE5-2	004 iE5-2
W	68	68	68	68	68	68
H	128	128	128	128	128	128
D	85	85	115	85	85	115
H1	124	124	124	124	124	124
W1	64	64	64	64	64	64
ϕ	4.2	4.2	4.2	4.2	4.2	4.2

*Note) Please use the M4 bolt in case this drive is installed into the panels.



Memo

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Memo

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Safety Instructions

- For your safety, please read user's manual thoroughly before operating.
- Contact the nearest authorized service facility for examination, repair, or adjustment.
- Please contact a qualified service technician when you need maintenance.
  Do not disassemble or repair by yourself!
- Any maintenance and inspection shall be performed by the personnel having expertise concerned.

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